DYNAMIC PHASE ALIGNMENT
METHODS AND APPARATUS

Background of the Invention

[0001]   This invention relates to methods and

5   apparatus for processing a received serial data signal,

and more particularly to methods and apparatus for

determining the phase of such a signal so that it can

be reliably sampled to recover its data content.

[0002]   Receiver circuitry may receive a serial data

10   signal with no accompanying information about the

timing of the individual data bits in that signal.

This timing information is sometimes referred to as the

phase of the signal. The receiver circuitry must

recover the data from the received signal. To do this,

15   the receiver circuitry needs to sample the received

signal during each data bit interval ("unit interval")

in that signal to determine whether the signal

currently represents a binary 1 or a binary 0.

Information about the phase of the signal is needed so

20   that the signal can be sampled at a time during each

unit interval that will give reliable results. For

example, it may be desired to sample the signal as

close to the center of each unit interval as possible.
Because the data signal is not received with any
accompanying phase information, the receiver circuitry
itself must derive the phase information it needs from

5   the received data signal. The process of determining
the phase of a received data signal may be referred to
as phase alignment; and because the phase of the
received signal may change over time, the phase
alignment may need to be dynamic to keep the results

10   current at all times.

[0003]   A known dynamic phase alignment ("DPA")
technique includes producing several candidate clock
signals, all of which have the same frequency (related
to the frequency of the received data signal), and each

15   of which has a unique phase. For example, there may be
eight candidate clock signals, the phases of which are
equally spaced over one clock signal cycle. Phase
detector circuitry is used to compare the phase of
transitions in the received data signal to the phase of

20   transitions in one of the candidate clock signals.
Assuming the phase detector does not detect a perfect
phase match (as it almost never does), the phase
detector circuitry keeps moving from one candidate
clock signal to the next trying to find the candidate

25   signal having the phase that will be best for use in
timing the sampling of the data signal.

[0004]   Typically the phase detector circuitry
quickly finds what it regards as currently the best (or
at least a very good) candidate clock signal for use in

30   controlling data signal sampling. But continued
operation of the phase detector circuitry also
typically causes it to switch to a different candidate
clock signal as it continues to search for the best

such signal to use. The new choice may in fact be somewhat better or somewhat worse than the old choice. In either case, as long as there is still some phase mismatch, the search for the best signal continues,

5 which may cause the phase detector to soon revert to its previous choice. In other words, even when the system is effectively at convergence, continued searching for a better candidate clock signal to use may cause the system to unproductively bounce back and

10 forth between two choices, one of which may be better than the other, but either of which can be used with acceptably good results. Although systems having the foregoing characteristic can operate very well, the above-described bouncing or hunting can be undesirable.

15 For example, it can increase noise in the system, and it can cause data signal interpretation errors that might not otherwise occur.

[0005] Examples of phase detector systems of the type described above are shown in such references as

20 Aung et al. U.S. patent application No. 09/805,843, filed March 13, 2001, Lee et al. U.S. patent application No. 10/059,014, filed January 29, 2002, Lee et al. U.S. patent 6,650,140, Venkata et al. U.S. patent application No. 10/195,229, filed July 11, 2002,

25 Venkata et al. U.S. patent application No. 10/273,899, filed October 16, 2002, Venkata et al. U.S. patent application No. 10/317,262, filed December 10, 2002, Lui et al. U.S. patent application No. 10/454,626, filed June 3, 2003, Venkata et al. U.S. patent

30 application No. 10/349,541, filed January 21, 2003, Venkata et al. U.S. patent application No. 10/637,982, filed August 8, 2003, Asaduzzaman et al. U.S. patent application No. 10/668,900, filed September 22, 2003,

and Asaduzzaman et al. U.S. patent application No. 10/672,901, filed September 26, 2003. These references also show examples of systems that can be modified in accordance with the principles of the present invention (e.g., to include the phase detector circuitry of this invention in place of the prior phase detector circuitry).

Summary of the Invention

[0006] Dynamic phase detector circuitry in accordance with this invention selects two phase-adjacent clock signals from a plurality of phase-distributed candidate clock signals. Different such selections may be made until it is found that transitions in the two selected clock signals are predominantly on respective opposite sides of transitions in the serial data signal with which phase alignment is desired. One of the two selected clock signals is further selected for use in controlling the timing with which the serial data signal is sampled to recover data from that signal. The consistency with which the two selected clock signals continue to have transitions on their respective opposite sides of the transitions in the serial data signal is monitored separately for each of the two selected signals. Different consistency measure thresholds are preferably used for each of the two signals, with the signal that is further selected for use in controlling the timing of data signal sampling preferably having the greater threshold value. As long as both of the two selected signals continue to have transitions that are predominantly on their respective opposite sides of the serial data signal transitions, and as long as the

consistency measure threshold for the further selected signal is not reached before the consistency measure threshold for the other of the two selected signals is reached, no change is made in any of the clock signal selections. In addition, a lock output signal may be produced under these conditions to indicate that the dynamic phase alignment is stable.

[0007] Further features of the invention, its nature and various advantages, will be more apparent from the accompanying drawings and the following detailed description.

Brief Description of the Drawings

[0008] FIG. 1 shows illustrative signal waveforms (all plotted along a common horizontal time scale) that are useful in explaining the invention.

[0009] FIG. 2 is a simplified schematic block diagram showing illustrative circuitry constructed in accordance with the invention.

[0010] FIG. 3 is a table showing illustrative modes of operation of circuitry of the type shown in FIG. 2 in accordance with the invention.

[0011] FIGS. 4a-4b are collectively a simplified flow chart showing further illustrative aspects of operation of circuitry of the type shown in FIG. 2 in accordance with the invention.

[0012] FIG. 5 shows more illustrative signal waveforms (all plotted along a common horizontal time scale) that are useful in explaining further aspects of the invention.

Detailed Description

[0013]   FIG. 1 illustrates typical and representative
signal conditions that can occur in either the prior
systems mentioned in the background section of this
specification or in a system in accordance with this
invention. A serial data signal DATAIN represents
successive bits of data. Each bit of data occupies one
"unit interval" or "UI" in the data signal. The data
signal does not necessarily transition (change in
level) at the beginning and end of each UI, but all
transitions in the data signal level are at the
boundaries between UIs. In FIG. 1 both possible levels
of DATAIN are shown for each UI, and the boundaries
between UIs are indicated by the crosses to show where
transitions can occur. Only one complete UI is shown
in FIG. 1, but it will be understood that this UI is
preceded and followed by many other UIs in what is
typically a long series of UIs, each of which is
immediately adjacent to the preceding and following UIs
in the series.

[0014]   FIG. 1 indicates the "optimal sampling point"
for the representative UI shown in that FIG. In the
particular example shown in FIG. 1 the optimal sampling
location is indicated to be the center of each UI. It
will be understood, however, that in other systems the
optimal sampling point may be somewhat earlier or
somewhat later than the center of each UI. Any desired
optimal sampling point can be accommodated by the
present invention.

[0015]   FIG. 1 also shows two representative
candidate clock signals on the same horizontal time
axis as DATAIN. These two candidate clock signals are
labelled "Phase X" and "Phase X + 45°", respectively.

The Phase X and Phase X + 45° signals are two phase-adjacent ones of eight candidate clock signals. All of these signals have the same frequency, which in this example is equal to the bit rate of the DATAIN signal.

5   Each of the eight candidate clock signals has a phase that is different from the phases of all of the other ones of those signals. These eight different phases are preferably equally distributed over one cycle of any one of the candidate clock signals. Thus the phase

10   difference between any two phase-adjacent candidate clock signals is 45° in this example. Although eight signals with 45° phase spacing are employed in the illustrative embodiment shown and described herein, it will be understood that any number of such signals

15   having any suitable phase spacing can be used instead if desired.

[0016]   In some prior phase alignment systems phase detector circuitry is used to compare the phase of transitions in the DATAIN signal with the phase of

20   transitions in candidate clock signals like those described above, taking the candidate signals one at a time. The objective is to find the one candidate clock signal having the phase that makes it best for use in timing the sampling of DATAIN to extract the data

25   information from that signal. In the example shown in FIG. 1 the prior phase detector circuitry may compare the phase of falling edges in a candidate clock signal with the phase of UI boundaries in the DATAIN signal. The candidate clock signal having falling edges that

30   are closest in phase to UI boundaries has rising edges that are closest to the center of the UIs. In the particular case shown in FIG. 1, the Phase X + 45° signal has falling edges that are closest in phase to

UI boundaries in DATAIN. The rising edges in Phase X + 45° are therefore closest to the center of the UIs and thus have the best timing for use in controlling sampling of DATAIN.

5 [0017]   After selecting Phase X + 45° for use in controlling sampling of DATAIN, the above-described prior phase detector circuitry will, however, continue to detect that the falling edges in Phase X + 45° are actually somewhat later in time or phase than the UI

10 boundaries in DATAIN. Eventually this will cause phase alignment circuitry of the above-described prior type to switch to the phase-adjacent candidate clock signal whose falling edges are earlier in time or phase than the UI boundaries in DATAIN. This means switching from

15 Phase X + 45° to Phase X as the signal selected for controlling the timing of DATAIN signal sampling. Although probably still an acceptable choice, Phase X is not as good a choice as Phase X + 45° because the positive-going transitions in Phase X are farther from

20 the center of UI than the positive-going transitions in Phase X + 45°.

[0018]   After operating with Phase X for some time, the fact that negative-going transitions in Phase X are ahead of UI boundaries in DATAIN will cause the above-

25 described prior phase alignment circuitry to switch back to using Phase X + 45° as the signal for controlling sampling of DATAIN.

[0019]   The above-described prior phase alignment circuitry will continue to switch back and forth

30 between Phase X + 45° and Phase X indefinitely (assuming that the UI boundaries in DATAIN remain between falling edges in these two candidate clock signals). This switching back and forth serves no

useful purpose, and it may have such disadvantages as increasing noise in the system and increasing the risk of false interpretation of bits in DATAIN.

[0020]   Illustrative dynamic phase alignment ("DPA") circuitry 10 in accordance with the present invention is shown in FIG. 2. This circuitry includes two phase detector circuits 20 and 30. Each of phase detector circuits 20 and 30 receives the DATAIN signal via one of its inputs. The other input to phase detector 20 is the candidate clock signal currently being used to control sampling of DATAIN. This candidate clock signal is sometimes referred to herein as the "current phase" signal. The other input to phase detector 30 is the candidate clock signal (sometimes referred to as the "next phase" signal) that is adjacent in phase to the current phase signal and that the current phase circuitry (elements 20 and 22) are pointing to as a possibly (although not necessarily) better choice for use in controlling sampling of DATAIN. (The manner in which this "pointing" is done will be explained later in this specification.) For example, in the situation illustrated by FIG. 1, the current phase signal might be Phase X + 45°, in which case the next phase signal would be Phase X.

[0021]   If phase detector 20 detects that a transition in DATAIN is later in time than a negative-going transition in the current phase signal, circuitry 20 outputs an "up" signal pulse on its UPA output lead to indicate that a better phase match might be achieved by selecting as the current phase signal the candidate clock signal having greater phase angle than the candidate clock signal currently selected as the current phase signal. Conversely, if phase detector 20

detects that a transition in DATAIN is earlier in time
than a negative-going transition in the current phase
signal, circuitry 20 outputs a "down" signal pulse on
its DNA output lead to indicate that a better phase

5   match might be achieved by selecting as the current
phase signal the candidate clock signal having a lower
phase angle than the candidate clock signal currently
selected as the current phase signal.

[0022]   Circuitry 22 may be counter and divider

10   circuitry. Circuitry 22 counts up in response to each
UPA pulse produced by circuitry 20. Circuitry 22
counts down in response to each DNA pulse. The count
contained by circuitry 22 at any given time during
counting operation of that circuitry is thus the net of

15   the UPA and DNA pulses it has received since it was
last reset. Circuitry 22 produces an output signal on
an F UPA output lead whenever the net count contained
in circuitry 22 is 28 UPA pulses. Circuitry 22
produces an output signal on an F DNA output lead

20   whenever the net count contained in circuitry 22 is 28
DNA pulses. The counter in circuitry 22 may be reset
to a neutral starting count each time such an F UPA or
F DNA output signal is produced. A counter in
circuitry 32 (described in more detail below) is also

25   reset whenever the counter in circuitry 22 is reset.

[0023]   Elements 30 and 32 are constructed and
operate similarly to what has been described above.
Circuitry 30 produces an UPB or DNB output pulse
whenever a transition in DATAIN is later or earlier,

30   respectively, than a negative-going transition in the
next phase signal. Circuitry 32 forms a net count of
the UPB and DNB pulses and outputs an F UPB or F DNB
signal whenever the net count contained in circuitry 32

is 14 UPB or DNB pulses, respectively. Again, the
counter in circuitry 32 may be reset to a neutral
starting count each time such an F UPB or F DNB output
signal is produced. The counter in circuitry 32 may
5   also be reset at other times, such as whenever the
counter in circuitry 22 is reset.

[0024]   The integration operations performed by
elements 22 and 32 (e.g., forming net counts of the up
and down pulses and then requiring the net counts to
10   reach thresholds of 28 or 14 before producing any
further output signals) prevent the system from trying
to be too responsive to phase differences between
DATAIN and the candidate clock signals applied to
elements 20 and 30. In addition, the use of different
15   thresholds in elements 22 and 32 (especially the use of
a smaller threshold (e.g., 14) in element 32 than in
element 22 (e.g., 28)) helps make the system more
likely to lock on one phase than to switch arbitrarily
between two phases as will be shown below. This
20   further improves the stability of the system in
accordance with the invention. (Later in this
specification it will be explained that the difference
in the thresholds mentioned above may not actually be
as great as the difference between 28 and 14.)

25   [0025]   Control circuitry 40 receives all of the
F UPA, F DNA, F UPB, and F DNB signals. On the basis
of those signals, circuitry 40 controls multiplexer
circuitry 50 to select the current phase signal and the
next phase signal from among the eight candidate clock
30   signals supplied to multiplexer circuitry 50 via leads
52. An illustrative selection control algorithm that
control circuitry 40 may implement in accordance with
the invention is shown in FIGS. 3 and 4a-4b.

[0026]   Each horizontal line in FIG. 3 illustrates
different possible conditions of the counts in circuits
22 and 32 when one or the other of those circuits
reaches its threshold for outputting one of the F UPA,
5   F DNA, F UPB, or F DNB signals. The channel with the
circuit 22 or 32 thus outputting one of these signals
is identified in the FIG. 3 column headed "Winner."
The two left-hand columns indicate the "polarity" of
the concurrent net counts in circuits 22 and 32,
10   respectively. The right-hand column indicates the
current-phase action (if any) taken or commanded by
circuitry 40 in response to the conditions indicated in
the first three columns. The possible, subsequent,
next-phase action taken or commanded by circuitry 40 is
15   illustrated by FIGS. 4a-4b, described later in this
specification.

[0027]   Considering first the first line in FIG. 3,
if both of circuits 22 and 32 are registering net UP
counts when either of those circuits reaches its
20   threshold (28 or 14, respectively) for outputting an
F UPA or F UPB signal, then control circuit 40 causes
multiplexer 50 to select a higher phase candidate clock
signal for the current phase signal. For example, if
the current phase signal was Phase X and the next phase
25   signal was Phase X + 45°, the new current phase signal
would be Phase X + 45°. It will be apparent from this
and the following discussion that to perform its
function, control circuit 40 needs to receive not only
signals telling it when one of circuits 22 and 32 has
30   reached its threshold and from which direction, but
also what the current state of the count in the other
one of circuits 22 and 32 is. For example, the F UPA,
F DNA, F UPB, and F DNB signals can include signals

indicating whether the count in the associated circuit 22 and 32 is currently trending up or trending down.

[0028]   The second line in FIG. 3 illustrates what may be thought of as a condition opposite that illustrated by the first line. This is a condition in which both of circuits 22 and 32 are registering net DN counts when either of those circuits reaches its threshold for outputting an F DNA or F DNB signal. When that type of condition is detected, control circuitry 40 causes multiplexer 50 to select for the current phase signal a candidate clock signal having lower phase. For example, if the current phase signal was Phase X and the next phase signal was Phase X + 45°, the current phase signal would become Phase X - 45°. As another example, if the current and next phase signals were Phase X + 45° and Phase X, respectively, the new current phase signal would be Phase X.

[0029]   The third line in FIG. 3 illustrates the following condition: Circuit 32 outputs an F DNB signal before circuit 22 reaches the count required for output of an F UPA signal. However, the net count in circuit 22 is UP. This indicates that the phase of DATAIN is between the phases of the current and next phase signals. It may additionally suggest that the phase of DATAIN is quite close to the phases of the current phase signal and farther from the phase of the next phase signal (because circuit 32 is receiving sufficiently predominant DNB pulses to reach its threshold count of 14, while circuit 22 is not receiving sufficiently predominant UPA pulses to (in the same time) reach its threshold count of 28). This further suggests that the current phase signal is

already the best available choice for use in sampling DATAIN. Accordingly, control circuit 40 does not change the signal selections being made by multiplexer 50, and may in addition produce an output "LOCK" signal

5 indicating to the circuitry making use of DPA circuitry 10 that the DPA circuitry is in a desirable, stable, "lock" condition.

[0030] The fourth line in FIG. 3 illustrates a condition somewhat like the third line condition,

10 except that in this case circuitry 22 reaches its UP threshold (28) and outputs an F UPA signal before circuitry 32 reaches its DN threshold (14). This again indicates that DATAIN has phase between the phases of the current and next phase signals. However, it also

15 suggests that the phase of DATAIN is closer to the phase of the next phase signal than to the phase of the current phase signal. Accordingly, control circuit 40 causes multiplexer 50 to select the next higher phase candidate clock signal for the current phase signal.

20 For example, if current phase was Phase X and next phase was Phase X + 45°, current phase becomes Phase X + 45°.

[0031] The fifth line in FIG. 3 is somewhat like the third line, except that in this case the current phase

25 signal has greater phase angle (e.g., Phase X + 45°) than the next phase signal (e.g. Phase X). Circuitry 32 reaches its UP threshold (14) and outputs an F UPB signal before circuitry 22 reaches its DN threshold (28). This condition indicates that the phase of

30 DATAIN is between the current and next phases. In addition, this condition tends to suggest that the phase of DATAIN is closer to the current phase than to the next phase. Control circuitry 40 therefore makes

no change in either the current phase signal or the
next phase signal, and it may also output a "LOCK"
signal as described above in connection with the third
line in FIG. 3.

5   [0032]   The last line in FIG. 3 bears the same kind
of relationship to the fourth line that the fifth line
bears to the third line. Again, the current phase
signal has greater phase angle than the next phase
signal. The phase of DATAIN is between the current
10 phase and the next phase. However, circuit 22 reaches
its DN threshold (28) and outputs an F DNA signal
before circuitry 32 reaches its UP threshold (14).
This suggests that the next phase signal is closer to
the phase of DATAIN than the current phase.
15 Accordingly, control circuitry 40 causes multiplexer 50
to select a new current phase signal having phase angle
that is decreased relative to the previously selected
current phase signal.

[0033]   The above discussion of FIG. 3 covers only
20 possible changes in the current phase signal. Whenever
there is a change in the current phase, the new next
phase signal is subsequently determined by the polarity
of an initial subsequent count of the counter in
circuitry 22. This can be done in the manner
25 illustrated by FIGS. 4a-4b. For example, after the
counters in both of circuits 22 and 32 are reset (step
112) (e.g., following a change in the current phase),
the counter in circuitry 32 is held in reset and only
the counter in circuitry 22 is released (step 114).
30 Steps 120, 122, 124, and 130 show that the counter in
circuitry 32 is held in reset until the counter in
circuitry 22 reaches +7 or -7. If +7 is reached, next
phase is selected (by element 50 in FIG. 2) as the

current phase +45° (step 122). If -7 is reached, next phase is selected (by element 50 in FIG. 2) as the current phase -45° (step 124). After next phase has been selected in this manner, the counter in circuit 32 is released from reset (step 130). Using a threshold like +/-7 in the selection of next phase helps prevent next phase from switching around too much.

[0034] Once next phase has been selected, the counters in circuits 22 and 32 compete by counting to 28 and 14, respectively (step 140). The step 132 intervening between steps 130 and 140 monitors the possibility of the counter in circuitry 22 falling below +7 or above -7. If that happens, the counter in circuitry 32 is reset (step 134) and the next phase selection process is repeated by returning to step 120. Thus the threshold difference between circuits 22 and 32 is not as great as it may at first appear to be, because the counter in circuitry 22 is always given a head start of 7 before the counter in circuitry 32 is released to begin counting. The threshold difference between circuits 22 and 32 is therefore only 7, not 14 as it may superficially appear to be.

[0035] When the counter in either of circuits 22 and 32 exceeds its threshold, control passes from step 140 to step 142. This step determines the action to be taken according to FIG. 3. If the action to be taken is a change in the current phase, that is done in step 152 and control then passes back to step 112. On the other hand, if the action to be taken is "lock," that is done in step 150, after which control passes back to step 112.

[0036] It is believed desirable for the next phase threshold (e.g., 14) to be less than the current phase

threshold (e.g., effectively 21, after the head start
of 7 given the counter in circuitry 22 before the
counter in circuitry 32 is released to begin counting
as described above) because this contributes to system

5   stability. Next phase should be farther from the phase
of DATAIN than current phase. When that is the case,
circuitry 32 should reach its relatively low threshold
before circuitry 22 reaches its relatively high
threshold, and under those conditions the system will

10   "lock" (i.e., not change the selections of current
phase and next phase). On the other hand, if circuitry
22 reaches its high threshold (effectively 21) before
circuitry 32 reaches its low threshold (14), there is a
need to change the current and next phase signal

15   selections because the current phase signal is not the
best one for use in controlling when the DATAIN signal
is sampled. It will be appreciated, however, that it
may not be necessary for circuits 22 and 32 to have
precisely this difference in thresholds. Good

20   operation may be achieved with thresholds that are
farther apart, not as far apart, or even equal to one
another.

[0037]   It will also be understood that FIGS. 3 and
4a-4b are only illustrative of how circuitry 40 may be

25   arranged to respond to various conditions in the
circuitry upstream from circuitry 40.

[0038]   Another desirable attribute of the circuitry
of the invention is that its resolution tends to
increase with jitter on the data. The circuit has the

30   tendency to settle in the better of the two best phases
with jitter on the data because jitter slows down the
counter 22/32 that is closer to the optimal sampling
point. This is illustrated by FIG. 5.

[0039]   In FIG. 5, next phase is closer to the
optimal sampling point. The next phase detector 30
will mostly be outputting DN pulses because next phase
is somewhat above the optimal sampling point. However,
because of the noise on the data, the next phase
detector will also output some UP pulses. The closer
next phase is to the sampling point, the more UP pulses
will occur when compared to DN pulses. However, total
DN pulses should be greater than UP pulses, assuming
the jitter is distributed in a Gaussian distribution
around the optimal sampling point and next phase is
above the optimal sampling point. The UP pulses slow
down the next phase counter 32 and make it more likely
that the current phase path 20/22 will reach its
threshold first, causing a switch to next phase. If
the current phase is closer to the optimal sampling
point, the current phase counter will be slowed down by
the jitter, making the circuit more likely to lock.
The end effect is that the circuit tends to settle in
the phase whose falling edge is closer to the data
transition point where the jitter is centered.

[0040]   It will be understood that the foregoing is
only illustrative of the principles of the invention,
and that various modifications can be made by those
skilled in the art without departing from the scope and
spirit of the invention. For example, the use of eight
candidate clock signals 52 is only illustrative, and a
larger or smaller number of such signals can be used
instead if desired. The candidate clock signals do not
have to have the same frequency as the bit rate of the
DATAIN signal. For example, the candidate clock
signals could have a frequency that is a multiple of
(e.g., two, three, or four times) the bit rate. In

such cases (or indeed in any case) the current phase
signal might not be used directly to control sampling
of the DATAIN signal, but might instead be used as a
pointer to another clock signal that is best for
5   sampling the DATAIN signal. For example, this other
clock signal could be another of the candidate clock
signals having a predetermined phase shift from the
current phase signal.